



- The fast and graphical interface makes all operations practical.
- Welding parameters are adjusted easily and quickly.
- With full trajectory learning, the robot arm can be dragged by hand to quickly create a position or trajectory.
- Teaching and programming processes are completed in a short time.
- Created trajectories can be easily converted into a welding procedure through graphical programming.
- The welding process package supports digital/analog signal and DeviceNet control.
- Parameters such as voltage, current, and baud rate can be configured quickly.
- Functions such as arc start, arc detection, wire forward/ backward, and gas control can be directly controlled.
- In emergency stop or pause situations, the robot arm immediately stops the welding.
- Collision detection reduces risks in hazardous environments.
- Compatible with linear, triangular, spiral, trapezoidal, and sinusoidal shapes

Weight (kg)	Kg	40
Payload (kg)	Kg	10
Working Radius (mm)	mm	1300
Max Reach (mm)	mm	1525
Rated Voltage (V)	V	DC48
Maximum Speed of TCP (m/sn)	m/sn	4
Repeatability (mm)	mm	±0.03
Communication		DI-16, DI/DO-16, AI/AO-2, ABZ Incremental Enc-1
IP Rating	IP	IP54
Temperature	°C	0°C-45°C
Power (W)	W	350
Materials		Aluminum alloy, ABS plastic

ADVANTAGES OF COBOT WELDING APPLICATIONS



EASY PROGRAMMING Fast teaching with hand guidance and an intuitive interface

thanks to its lightweight structure

Can be easily moved to different stations

PORTABILITY



FAST INSTALLATION Requires minimal integration: short commissioning time

SAFE OPERATION



LOW CELL COST Does not require protective barriers or complex safety systems



FLEXIBLE PRODUCTION

Fast job changeover, high efficiency in low and medium-volume production





REPEATABLE WELD QUALITY Stable arc and precise control ensure consistent weld quality

STANDARD & OPTIONAL EQUIPMENTS

This order code includes the cobot, control unit, and pendant.







Pendant



PoWer MIG GPS 5000-R (Optional)



Welding Table (Optional)



Fixture Set (Optional)



Laser Sensor (Optional)

